

# eQart®

BY



## eQart software release 2.0

### What's new in version 2.0

- Overhauled the line-follow algorithm to increase robustness
- Added a new line-follow function called edge-detection for rough environments
- A completely new feature called mission-planner that lets you plan consecutive actions for the eQart to perform
- A new feature that alerts the operator with a text when the battery is low
- Time monitoring of motor run hours
- When the eQart is not used it will go into sleep mode to conserve battery
- Added icon to display tablet battery

### What's fixed?

- Improved and more reliable communication between the cockpit and eQart
- Improved detection of junctions
- Fixed a bug where the eQart would sometimes not switch directions automatically in navigation
- Fixed a bug where the eQart would sometimes drive over and ignore the station tag